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# CSCI2510 Computer Organization Tutorial 07: Subroutine in MASM

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### Outline



Subroutine Revisited

Stack Frame

Greatest Common Divisor

• Basic concepts:



- After a subroutine calling, the subroutine is said to return to the program that called it.
  - Continuing immediately after the instruction that called the subroutine.
- Provision must be made for returning to the appropriate location.
  - the contents of the PC must be saved by the call instruction to enable correct return to the calling program







- Divide/Decrease and conquer
- Reuse codes
- Make variable namespace clean

# Divide/Decrease and conquer



- Philosophy of multi-branched recursion
- A divide/decrease and conquer algorithm works by
  - Divide: recursively breaking down a problem into two or more sub-problems of the same or related type, until these become simple enough to be solved directly.
  - Conquer: independently solve each sub-problem.
  - Combine (for divide and conquer): the solutions to the sub-problems are combined to give a solution to the original problem.
- E.g.: (1) Binary search (2) Merge sort (3) Greatest common divisor, etc...

### **Examples**



• Binary search: decrease and conquer algorithm



Ref: https://www.topcoder.com/blog/binary-stride-a-variant-on-binary-search/

### **Examples**



• Merge sort: divide and conquer algorithm



Ref: https://medium.com/basecs/making-sense-of-merge-sort-part-1-49649a143478



• Think about we want to implement following function:



- Observation: the return address needed for the first return is the last one generated in the nested calls.
  - Last-in-first-out (LIFO) order -> Stack



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#### • Processor **stack** is useful to store subroutine linkage

Main	program					Second subroutine				
2000		PUSH PUSH	PARAM2 offset PARAM1	Place parameters on stack.	3000	SUB2:	PUSH MOV	EBP EBP, ESP	Save frame pointer register Load the frame pointer	
2008 2012 2016 2020		ADD next inst	[RESULT] ESP, 4 truction	Store result. Restore stack level.			PUSH MOV :	R0, R1 R0, 8[EBP]	Save registers (Abbreviated!) Get the parameter.	
First	subroutine				MOV	8[EBP], R1	Place SUB2 result on stack.			
2100 2104 2108	SUB1:	PUSH MOV PUSH MOV MOV	EBP EBP, ESP R0, R1, R2, R3 R0, 8[EBP] R1, 12[EBP]	Save frame pointer register Load the frame pointer Save registers (Abbreviated!) Get first parameter. Get second parameter.			POP POP RET	R1, R0 EBP	Restore registers (Abbreviated!) Restore frame pointer register. Return to SUB1.	
2160 2164		push CALL POP	PARAM3 SUB2 R2	Place a parameter on stack. Pop SUB2result into R2.			Star	ndard form!		
	P1:	MOV POP POP RET	8[EBP], R3 R3, R2, R1, R0 EBP	Place answer on stack.						







- Conservation of stack level:
  - The major concern is the value of ESP, it is always modified by PUSH and POP instructions.
- Preservation of registers' contents
  - Save and restore the registers' contents before and after they are used for other purposes
  - E.g. in a procedure call



- In mathematics, the greatest common divisor (GCD) of two or more integers, when at least one of them is not zero, is the largest positive integer that divides the numbers without a remainder.
- E.g., GCD(60, 36) = 12.
- You can definitely enumerate all divisors of each number and then pick up the largest common one, but it's not efficient enough.



• A simple way to find GCD is to factorize both numbers and multiply common factors.

- GCD = Multiplication of common factors = 2 x 2 x 3 = 12
- Recursive algorithm:
  - gcd(a, 0) = a
  - gcd(a, b) = gcd(b, a mod b)
  - E.g., gcd(48, 18) = gcd(18,12) = gcd(12,6) = gcd(6,0) = 6
- Question: what is the implementation in C/C++?

# **Euclid's Algorithm**



• Euclid's Algorithm in C/C++

```
□ int GreatestCommonDivisor(int a, int b)
 {
     if (a < b)
      ł
          int temp = a;
          a = b;
          b = temp;
     }
     if (b == 0)
          return a;
     else
          return GreatestCommonDivisor(b, a % b);
 }
```

4 parts: (1) main func of gcd (2) func of check order
(3) func of divide recursively (4) how to end



- Complete the Euclid's algorithm in MASM:
- Hints:
  - Complete (2) (3) (4) asseparate functions
  - for "div src"
  - EAX = EDX:EAX / src
  - EDX = EDX:EAX % src

```
gcd proc
push ebp
mov ebp, esp
push ebx
push eax
mov eax, 8[ebp]
mov ebx, 12[ebp]
```

```
; Fill here!
; Put the result in ecx
```

return:

```
pop eax
pop ebx
pop ebp
ret
gcd endp
```



gcd proc push ebp mov ebp, esp push ebx push eax mov eax, 8[ebp] mov ebx, 12[ebp]	]	xor edx, edx idiv ebx push ebx push edx call gcd add esp, 8 jmp return	; edx = a % b
order: cmp eax, ebx jge divide mov ecx, eax mov eax, ebx mov ebx, ecx	; a < b	base: mov ecx, eax return: pop eax pop ebx	
divide: cmp ebx, 0	; a >= b	pop ebp ret gcd endp	



 Actually there is a direct implementation of GCD, why still using subroutine?

 What if you want to find GCD of 4 integers? Is that easy to modify with this implementation? NO!

```
invoke crt_printf, addr PrintFormat1
invoke crt_scanf, addr ScanFormat, addr Int1
invoke crt_printf, addr PrintFormat2
invoke crt_scanf, addr ScanFormat, addr Int2
mov eax, Int1
mov ebx, Int2
```

```
order:
```

```
cmp eax, ebx
jge divide
mov ecx, eax ; a < b
mov eax, ebx
mov ebx, ecx</pre>
```

```
divide: ; a >= b
cmp ebx, 0
je output
xor edx, edx
idiv ebx ; edx = a % b
mov eax, ebx ; a = b
mov ebx, edx ; b = a % b
jmp order
```

output:

invoke crt\_printf, addr PrintFormat3, Int1, Int2, eax invoke ExitProcess, NULL end start



- Benefits of subroutine/function again:
  - Divide and conquer
  - Reuse codes
  - Make variable namespace clean
- Exercise: use the "subroutine" we just define to get the GCD of 4 integers.
- GCD(a, b, c, d) = GCD(a, GCD(b, GCD(c, d)))

# Summary



Subroutine Revisited

Stack Frame

Greatest Common Divisor